Control and Cybenertics

VOL. 17 (1988) No. 1

A counterexample to transformations in multiphase and sequential linear goal programming

by

WŁODZIMIERZ OGRYCZAK

Warsaw University Institute of Informatics PKiN VIII p. 850 00-901 Warsaw, Poland

We consider the lexicographic linear goal programming model. The two most common solution techniques to this model are the sequential process and the multiphase process. Both the methods produce, obviously, the same solution but the interior elements of the specific tableaus differ significantly. Markowski and Ignizio proposed an algorithm for transformation of the sequential tableau into the multiphase one and vice-versa. We present an example which shows failure of this algorithm with respect to saving optimality (dual feasibility) of the transformed tableau while degeneracy occurs.

1. Introduction

In this note we deal with lexicographic linear goal programming, i.e., with the specific form of linear goal programming wherein one seeks the lexicographic minimum of an ordered set of goal deviations. This approach, also described as preemptive priority based goal programming, is widely used in multiobjective optimization.

The lexicographic linear goal programming (LGP) problem is usually given as follows.

Find a vector x so as to lexicographically minimize

$$a = [g_1(n, p), g_2(n, p), \dots, g_K(n, p)]^T,$$
(1)

subject to

$$\sum_{i \in J} c_{ij} x_j + n_i - p_i = b_i \quad \text{for } i \in I,$$
(2)

$$x \ge 0, \quad n \ge 0, \quad p \ge 0, \tag{3}$$

where

J — set of decision variable indices,

W. OGRYCZAK

I — set of goal indices,

 $x_j - j$ -th decision variable,

 c_{ij} — coefficient of variable j in the i-th goal constraint,

 b_i — target for goal *i*,

 n_i — negative deviation for goal *i*,

 p_i — positive deviation for goal *i*,

 $g_k(n, p)$ — linear function of the deviation variables to be minimized at priority k.

The two most common solution techniques for LGP problems are: sequential process (known as sequential linear GP or SLGP [2]) and the modified simplex procedure which is known as the multiphase process or MLGP [1]. Both the methods have the same conceptional basis.

Due to lexicographic minimization, the optimal solution to the LGP problem is defined as follows:

1) find S_1 as the optimal set to the problem

 $P_1: \min \{g_1(n, p) \text{ subject to } (2) \text{ and } (3)\},\$

2) for k = 2, 3, ..., K find S_k as the optimal set to the problem $P_k: \min \{g_k(n, p) \text{ subject to } (2), (3) \text{ and } x \in S_{k-1}\},\$

3) any vector of the set S_K is optimal to the LGP problem.

Both the methods SLGP and MLGP are based on the above scheme. They differ only in techniques used for introducing the additional requirement $x \in S_{k-1}$ into the problem P_k .

In the SLGP approach the requirement $x \in S_{k-1}$ is represented by the equality system

$$g_1(n, p) = \overline{a}_1$$
$$g_2(n, p) = \overline{a}_2$$
$$\dots$$

 $g_{k-1}(n,p)=\bar{a}_{k-1}$

where \bar{a}_i denotes the optimal value to the problem P_i . This method is very convenient when the standard simplex codes are used. On the other hand, sensitivity and parametric analysis is extremely difficult in the SLGP approach since a dual solution to the LGP problem is then not available.

The MLGP method utilizes specifity of the simplex algorithm for introducing the requirement $x \in S_{k-1}$. Namely, only variables having all the reduced costs (optimality indices [1]) $I_{1,s}$, $I_{2,s}$, ..., $I_{k-1,s}$ equaled to zero are allowed to be positive in the problem P_k . Such an approach is equivalent to the lexicographic simplex method [3]. The optimal MLGP tableau contains a dual optimal solution to the LGP problem, so that sensitivity and parametric analysis can be easily carry out in the MLGP method. There are, however, difficulties with using standard simplex codes for implementation of this method. Whether one employs the SLGP or MLGP method the final solutions to the LGP problem are, obviously, the same. However, the interior elements of the specific tableaus will differ considerably. Markowski and Ignizio [4] proposed some algorithm which allows to transform the SLGP tableau into the MLGP tableau. Such a transformation is very useful since it makes possible to utilize extremely efficient standard simplex codes for solving the problem via SLGP approach and next to perform sensitivity analysis using the MLGP tableau. Unfortunately, we have found out that the algorithm fails while degeneracy occurs. Namely, for some problems it transforms the optimal (final) SLGP tableau into a MLGP tableau which does not satisfy optimality conditions (i.e., generated dual solution is infeasible). In this note we present such an example.

2. The counterexample

Consider the following LGP problem lexmin $[(n_1+n_2), (n_2+p_2+n_3)]^T$ subject to

$$x_{1} + +n_{1} - p_{1} = 1$$

$$x_{1} + x_{2} + n_{2} - p_{2} = 2$$

$$x_{2} + n_{3} - p_{3} = 1$$

$$x \ge 0, \quad n \ge 0, \quad p \ge 0$$

We solve this problem via the SLGP approach. First, the problem P_1 is solved, i.e., the achievement function $a_1 = n_1 + n_2$ is minimized. The initial simplex tableau appears in Table 1 (in the same form as in [4]).

Table 1. Priority level one: initial tableau

	x ₁	x2	<i>p</i> ₁	P2	P3		
n_1	1	0	-1	0	0	1	
n2	1	1	0	-1	0	2	
<i>n</i> ₃	0	1	0	0	-1	1	
	2	1	-1	-1	0	3	

 x_1 enters the basis, replacing n_1 , and thereby yielding the second tableau given in Table 2.

Table 2. Priority level one: second tableau

	x2	<i>n</i> ₁	<i>P</i> ₁	P2	. P3	
<i>x</i> ₁	0	1	-1	0	0	1
n2	1	-1	1	-1	0	1
n3	1	0	0	0	-1	1
18.3	1	-2	1	-1	0	1

Now x_2 is chosen to enter the basis and n_2 leaves the basis. The iteration is performed to yield the tableau given in Table 3.

	<i>n</i> ₁	<i>n</i> ₂	<i>p</i> ₁	<i>P</i> ₂	<i>P</i> ₃		
x_1	1	0	-1	0	0	1	
x2	-1	1	1	-1	0	1	
<i>n</i> ₃	1	-1	-1	1	-1	0	
	-1	-1	0	0	0	0	

Table	3.	Priority	level	one:	third	tableau
TRAIL	~	a monthly		Unio.		THE PLANE OF

The last tableau is optimal to the problem P_1 (priority level one). The solution is: $x = (1, 1)^T$, $n = (0, 0)^T$, $p = (0, 0)^T$ and $a_1 = 0$.

Next we solve the problem P_2 . Similarly as in [4], we introduce two additional equalities:

$$-n_1 - n_2 + r_- = 0$$
$$n_1 + n_2 + r_+ = 0$$

and compute reduced costs for the achievement function

$$a_2 = n_2 + p_2 + n_3$$

The initial tableau to the problem P_2 appears in Table 4.

Table 4. Priority level two: initial tableau.

					1	
_	<i>n</i> ₁	<i>n</i> ₂	<i>P</i> ₁	<i>P</i> ₂	<i>p</i> ₃	
<i>x</i> ₁	1	0	-1	0	0	1
x2	-1	1	1	-1	0	1
<i>n</i> ₃	1	-1	-1	1	-1	0
r	-1	-1	0	0	0	0
<i>r</i> +	1	1	0	0	0	0
	1	-2	-1	0	-1	0

This tableau is nonoptimal. The variable n_1 enters basis, replacing n_3 , and thereby yielding the second tableau given in Table 5.

Table 5. Priority level two: second (final) tableau.

					1	
	n ₂	<i>n</i> ₃	<i>P</i> ₁	<i>p</i> ₂	<i>P</i> ₃	-
<i>x</i> ₁	1	-1	0	-1	1	1
x_2	0	1	0	0	-1	1
n1	-1	1	-1	1	-1	0
r_	-2	1	-1	1	-1	0
r +	2	-1	1	-1	1	0
•	-1	-1	0	-1	0	0

The last tableau proves to be optimal to the problem P_2 and thereby it is an SLGP final tableau. The optimal solution to the original LGP problem is:

$$\bar{x} = (1, 1)^T$$
, $\bar{n} = (0, 0)^T$, $\bar{p} = (0, 0)^T$ and $\bar{a} = (0, 0)^T$.

We now transform Table 5 into the corresponding MLGP tableau using the algorithm proposed in [4]. The main operation performed in the algorithm depends on forcing r_{-} and r_{+} into the basis. In our case, however, r_{-} and r_{+} have already stayed in the basis. So, the algorithm transforms only form of the tableau without any change of the basis structure. In effect we get the MLGP tableau given in Table 6. The tableau is evidently nonoptimal since there are some positive elements in the P_{1} index row.

		P2 P1	1 1	1 0	0 0	1 0	0	14
P2	<i>P</i> 1	V	n ₂	<i>n</i> ₃	<i>p</i> ₁	<i>p</i> ₂	<i>P</i> ₃	Б
0	0	x1	1	-1	0	-1	1	1
0	0	x2	0	1	0	0	-1	1
0	1	<i>n</i> ₁	-1	1	-1	1	-1	0
		P1	-2	1	-1	1	-1	0
		P2	-1	-1	0	-1	0	0

Table 6. Final SLGP tableau transformed into the MLGP form

In other words, we get a tableau which generates an optimal solution to the LGP problem but the dual solution generated by the tableau is infeasible and cannot be used in sensitivity analysis. This phenomenon can be easily explained by careful analysis of the transformation proposed in [4]. As we have already mentioned the main operation performed in the algorithm depends on forcing r_{-} and r_{+} variables into the basis. Such an operation guarantees that the transformation yields some basis to the optimal solution of the MLGP problem. However, if degeneracy occurs then some bases to the optimal solution can be nonoptimal. So, Markowski and Ignizio use degeneracy of the SLGP problem for forcing the r_{-} and r_{+} variables into basis and, simultaneously, they ignore consequences of degeneracy in the original LGP problem. Thus advantages of the transformation proposed in [4] seem to be limited to rather theoretical class of nondegenerated LGP problems whereas real-life LGP problems are usually strongly degenerated.

Moreover, note that the basis consisting of the variables x_1 , x_2 and n_1 is optimal in the SLGP approach and it is nonoptimal in the MLGP approach. One can easily verify that the tableau given in Table 4, which is nonoptimal to the SLGP approach, would be transformed into an optimal MLGP tableau. So, the basis optimal in one approach can be nonoptimal

in the second approach and vice versa. The above proves that these two approaches to the LGP problems should be regarded as inconvertible with respect to optimal basis structure.

References

- [1] IGNIZIO J. P. Goal Programming and Extensions. Heath, Lexington, Mass., 1976.
- [2] IGNIZIO J. P., PERLIS J. M. Sequential Linear Goal Programming: Implementation via MPSX. Comput. Ops Res. 3 (1980), 217-225.
- [3] ISERMANN H. Linear Lexicographic Optimization. OR Spektrum 4 (1982), 223-228.
- [4] MARKOWSKI C. A., IGNIZIO J. P. Duality and Transformation in Multiphase and Sequential Linear Goal Programming. Comput. Ops Res. 10 (1983), 321–333.

Received, July 1987.

Kontrprzykład na przekształcenia tablic sympleksowych w hierarchicznym i wielofazowym podejściu do leksykograficznego programowania celowego

Leksykograficzne programowanie celowe (LPC) jest szeroko stosowanym narzędziem analizy problemów wielokryterialnych. Istnieją dwie podstawowe metody rozwiązywania zadań LPC: optymalizacja hierarchiczna i wielofazowy algorytm sympleks. Oba podejścia wyznaczają te same wektory optymalne, ale odpowiadają im różne tablice sympleksowe. Tablica sympleksowa dla wielofazowego algorytmu sympleks zawiera jednocześnie rozwiązanie dualne i inne elementy potrzebne do analizy wrażliwości. Własności tej nie posiada tablica otrzymana w wyniku realizacji łatwiej impelementowanej optymalizacji hierarchicznej. Okazuje się, że nie ma możliwości wzajemnego przekształcania tych tablic (po rozwiązaniu zadania), gdyż każda z nich może być generowana przez inną bazę optymalną.

Контрпример преобразования симплексных таблиц в иерархическом и многофазном подходе к лексикографическому целевому программированию

Лексикографическое целевое программирование (ЛЦП) является широкоприменяемым инструментом анализа многокритериальных задач. Существуют два основные метода решения задач ЛЦП: иерархическая оптимизация и многофазный симплекс-алгоритм. Оба подхода определяют те же оптимальные векторы, однако им соответствуют разные симплексные таблицы. Симплексная таблица для многофазного симплекс-алгоритма одновременно содержит дуальное решение и другие элементы, необходимые для анализа чувствительности. Этим свойством не обладает таблица получаемая в результате реализации, более удобной в применении, иерархической оптимизации. Оказывается, что «тсутствует возможность взаимного преобразования этих таблиц (после решения задачи), поскольку каждая из них может быть генерирована другой оптимальной базой.