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Some results for the reflection problems in Hilbert spaces^{*}

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Abstract: This work is concerned with existence and uniqueness of a solution of a stochastic variational inequality on closed convex bounded subsets with nonempty interior and smooth boundary of a Hilbert space H (the reflection problem).

Keywords: stochastic variational inequality, Wiener processes in Hilbert spaces, convex sets, strong solutions.

1. Introduction

Let H be a separable Hilbert space (with scalar product (\cdot, \cdot) and norm denoted by $|\cdot|$). We are given a closed convex subset K of H with non empty interior \mathring{K} . We denote by I_K the indicator function of K,

$$I_K(x) = \begin{cases} 0 & \text{if } x \in K. \\ +\infty & \text{if } x \notin K \end{cases}$$

and by ∂I_K the sub-differential of I_K (see, e.g., Barbu, 1993),

$$\partial I_K(x) = \{ z \in H : (z, x - y) \ge 0, \quad \forall y \in K \}, \quad x \in H.$$

We have

$$\partial I_K(x) \begin{cases} = \{0\} & \text{if } x \in \mathring{K}, \\ = N_K(x) & \text{if } x \in \partial K, \\ = \emptyset & \text{if } x \notin K, \end{cases}$$

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where $N_K(x)$ is the normal cone of K at x. We are concerned here with the stochastic variational inequality

$$\begin{cases} dX(t) + (AX(t) + F(X(t)) + \partial I_K(X(t))) dt \ni \sqrt{Q} \ dW(t) \\ X(0) = x \in K. \end{cases}$$
(1)

Formally, equation (1) can be represented as

$$\begin{cases} dX(t) + (AX(t) + F(X(t))dt = \sqrt{Q} \ dW(t) \ \text{in} \ \{t \in [0, T] : \ X(t) \in \check{K}\}, \\ dX(t) + (AX(t) + F(X(t)) + \zeta(t))dt = \sqrt{Q} \ dW(t) \\ & \text{in} \ \{t \in [0, T] : \ X(t) \in \partial K\}, \\ X(0) = x \in K, \end{cases}$$

$$(2)$$

where $\zeta(t) \in N_K(X(t))$ for all $t \in [0, T]$. For a precise definition of solution see Definition 1 below.

- HYPOTHESIS 1 (i) $A: D(A) \subset H \to H$ is a linear self-adjoint operator on H such that A^{-1} is compact and $(Ax, x) \geq \delta |x|^2, \forall x \in D(A)$ for some $\delta > 0$.
- (ii) $Q: H \to H$ is a linear, bounded, positive and self-adjoint operator on H such that $Qe^{tA} = e^{tA}Q$ for all $t \ge 0$.
- (iii) $Q(H) \subset D(A)$ and $\operatorname{Tr}[AQ] < \infty$.
- (iv) $F: H \to H$ is a Lipschitzian mapping such that for some $\gamma > 0$ we have

$$(F(x), x) \ge -\gamma, \quad \forall x \in H.$$

(v) W is a cylindrical Wiener process on H of the form

$$W(t) = \sum_{k=1}^{\infty} \mu_k \beta_k(t) e_k, \quad t \ge 0,$$

where $\{\beta_k\}$ is a sequence of mutually independent real Brownian motions on a filtered probability spaces $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t\geq 0}, \mathbb{P})$ (see Da Prato, 2004) and $\{e_k\}$ is an orthonormal basis in H, which will be taken as a system of eigen-functions for A for simplicity, i.e.

$$Ae_k = \alpha_k e_k, \quad \forall \ k \in \mathbb{N}.$$

(vi) $0 \in \mathring{K}$.

In most specific examples $H = L^2(\mathcal{O})$, A is an elliptic operator on \mathcal{O} with appropriate boundary conditions, F is a Nemitski operator on $L^2(\mathcal{O})$ (see Section 5 below).

Under Hypothesis 1 the stochastic convolution $W_A(t)$,

$$W_A(t) = \int_0^t e^{-A(t-s)} \sqrt{Q} \, dW(s), \quad \forall t \ge 0$$

is a well defined mean square continuous process in $V = D(A^{1/2})$ and (see Da Prato, 2004),

$$\mathbb{E}\sup_{t\in[0,T]}\|W_A(t)\|^2 < +\infty.$$
(3)

Assumption (iii) is, of course, quite restrictive but it is essential for our approach since it implies continuity of $W_A : [0, +\infty) \to D(A^{1/2})$.

The existence and uniqueness of a strong solution X to equation (1) was an open problem except for the finite-dimensional case (Barbu and Da Prato, 2008; Cépa, 1994, 1998) and few special cases, for instance $H = L^2(0, 1)$, $A = -\Delta$, $K = \{x \in H : x \geq -\sigma \text{ a.e. on } (0, 1)\}$ where $\sigma \geq 0$ (see Haussmann and Pardoux, 1989; Nualart and Pardoux, 1992; Zambotti, 2001; as well as Barbu and Rascanu, 1997, Rascanu, 1996, and Zhang, 1997).

In this paper we prove the existence and uniqueness of a solution of 1 under Hypothesis 1.

Then we consider the transition semigroup $P_t : C_b(H) \to C_b(H)$

$$P_t\varphi(x) = \mathbb{E}[\varphi(X(t,x))], \quad x \in K, \tag{4}$$

where X = X(t, x) is the solution of (1) and $C_b(H)$ denotes the space of all mappings from H into \mathbb{R} which are uniformly continuous and bounded. We prove existence and, in some cases, uniqueness of an invariant measure ν of P_t . Finally we consider the infinitesimal generator N of P_t in $L^2(H, \nu)$, i.e.

$$D(N) = \left\{ \varphi \in L^2(H,\nu) : \exists \lim_{t \to 0} \frac{1}{t} \left(P_t \varphi - \varphi \right) \text{ in } L^2(H,\nu) \right\},$$

and

$$N\varphi = \lim_{t \to 0} \frac{1}{t} (P_t \varphi - \varphi) \text{ in } L^2(H, \nu), \quad \forall \varphi \in D(N).$$

It is an interesting problem to see the relationship between the abstract operator N and the differential operator

$$N_0\varphi = \frac{1}{2} \operatorname{Tr} \left[QD^2\varphi\right] - (x, AD\varphi) - (F(x), D\varphi), \quad \forall \varphi \in D(N_0),$$
(5)

with the domain

$$D(N_0) = \{ \varphi \in D(N) \cap C_b^2(H) : AD\varphi \in C_b^1(H), \ (D_\varphi(x), N_K(x)) = 0, \ \forall \ x \in \partial K \},\$$

where $N_K(x)$ is the normal cone of K at x.

In Section 4 we prove that N_0 is a section of N (Theorem 2). It would be interesting to show that $D(N_0)$ is a core for N. This is indeed the case if H is finite-dimensional (see Barbu and Da Prato, 2008). The problem is open when H is infinite-dimensional as in the present case.

Notations

We shall denote by C([0,T]; H) the space of all continuous functions from [0,T] to H and by BV([0,T]; H) the space of all functions with bounded variation from [0,T] to H.

We set $V = D(A^{1/2})$ with norm $\|\cdot\|$ and denote by V' the dual of V in the pairing induced by the scalar product (\cdot, \cdot) of H. We have $V \subset H \subset V'$ algebraically and topologically.

By $C_W([0,T];H)$, $L^2_W([0,T];V)$, $L^2_W([0,T];V')$ we shall denote standard spaces of adapted processes on [0,T] (see Da Prato, 2004, 2006; Da Prato and Zabczyk, 1996). Π_K is the projection on K.

By $D\varphi$ and $D^2\varphi$ we shall denote the Gâteaux derivatives of a function φ : $H \to \mathbb{R}$ of first and second order.

2. Existence and uniqueness for equation (1)

We shall assume here that Hypothesis 1 holds.

DEFINITION 1 The adapted process $X \in C_W([0,T];H) \cap L^2_W(0,T;V)$ is said to be a strong solution to (1) if there are functions $Y \in C_W([0,T];H) \cap L^2_W(0,T;V)$ and $\eta \in BV([0,T];H)$ such that,

(i) We have

$$X(t) = Y(t) + W_A(t), \quad \text{a.e. in } \Omega \times [0, T] \times H, \quad \mathbb{P}\text{-a.s.}$$
(6)

- (ii) $X(t) \in K$ for all $t \in [0, T]$.
- (iii) We have

$$Y(t) + \int_0^t (AY(s) + F(X(s)))ds + \eta(t) = x, \quad \forall \ t \in [0, T], \ \mathbb{P}\text{-a.e.}$$
(7)

(iv) For all $t \in [0,T]$ and $Z \in C([0,T];K)$

$$\int_0^t (d\eta(s), X(s) - Z(s)) ds \ge 0, \ \mathbb{P}\text{-a.e.}.$$
(8)

In (8) $\int_0^t (d\eta(s), X(s) - Z(s)) ds$ is the Stieltjes integral with respect to η . Note that by Hypothesis 1 it follows that V is compactly embedded in H.

THEOREM 1 Under Hypothesis 1 there is a unique strong solution to equation (1). Proof. Existence. We start with the approximating equation

$$\begin{cases} dX_{\epsilon} + (AX_{\epsilon} + F(X_{\epsilon}) + \beta_{\epsilon}(X_{\epsilon}))dt = \sqrt{Q} \ dW \\ X_{\epsilon}(0) = x, \end{cases}$$
(9)

where β_{ϵ} is the Yosida approximation of ∂I_K ,

$$\beta_{\epsilon}(x) = \frac{1}{\epsilon} \ (x - \Pi_K(x)), \quad \forall \ x \in H, \ \epsilon > 0.$$

Equation (9) has a unique strong solution $X_{\epsilon} \in C_W([0,T];H)$ such that $Y_{\epsilon} := X_{\epsilon} - W_A$ belongs to $L^2_W(0,T;H)$. We can rewrite (9) as

$$\begin{cases} \frac{dY_{\epsilon}}{dt} + AY_{\epsilon} + F(X_{\epsilon}) + \beta_{\epsilon}(X_{\epsilon}) = 0, \\ Y_{\epsilon}(0) = x, \end{cases}$$
(10)

which is considered for a fixed $\omega \in \Omega$. Since by Hypotheses 1(vi), $0 \in \mathring{K}$ there is $\rho > 0$ such that

$$(\beta_{\epsilon}(x), x - \rho\theta) \ge 0, \quad \forall \ \theta \in H, \ |\theta| = 1.$$

This yields

$$\rho|\beta_{\epsilon}(x)| \le (\beta_{\epsilon}(x), x), \quad \forall x \in H.$$
(11)

Step 1. There exists $C = C(\omega) > 0$ such that

$$|Y_{\epsilon}(t)|^{2} + \int_{0}^{t} ||Y_{\epsilon}(s)||^{2} ds + \int_{0}^{t} |\beta_{\epsilon}(X_{\epsilon}(s))| ds \leq C.$$

$$(12)$$

Indeed, multiplying (10) by $Y_{\epsilon}(s)$, integrating over (0, t) and taking into account (11), yields

$$\frac{1}{2} |Y_{\epsilon}(t)|^{2} + \int_{0}^{t} ||Y_{\epsilon}(s)||^{2} ds + \rho \int_{0}^{t} |\beta_{\epsilon}(X_{\epsilon}(s))| ds
\leq \frac{1}{2} |x|^{2} + \gamma \int_{0}^{t} |X_{\epsilon}(s)|^{2} ds + \int_{0}^{t} (F(X_{\epsilon}(s)) + \beta_{\epsilon}(X_{\epsilon}(s)), W_{A}(s)) ds.$$
(13)

In order to estimate the last term in (13), we recall (3) and choose a decomposition $0 < t_1 < \cdots < t_N = t$ of [0, t] such that for $t, s \in [t_{i-1}, t_i]$ we have

$$|W_A(t) - W_A(s)| \le \frac{\rho}{2}.$$

Then we write

$$\int_0^t (\beta_\epsilon(X_\epsilon(s)), W_A(s)) ds = \sum_{i=1}^N \int_{t_{i-1}}^{t_i} (\beta_\epsilon(X_\epsilon(s)), W_A(s) - W_A(t_i)) ds + \sum_{i=1}^N \left(W_A(t_i), \int_{t_{i-1}}^{t_i} \beta_\epsilon(X_\epsilon(s)) ds \right).$$

Consequently,

$$\int_0^t (\beta_{\epsilon}(X_{\epsilon}(s)), W_A(s)) ds \leq \frac{\rho}{2} \int_0^t |\beta_{\epsilon}(X_{\epsilon}(s))| ds$$
$$+ \left| \sum_{i=1}^N \left(W_A(t_i), \int_{t_{i-1}}^{t_i} (AY_{\epsilon}(s) + F(X_{\epsilon}(s))) ds + Y_{\epsilon}(t_i) - Y_{\epsilon}(t_{i-1}) \right) \right|$$

Now, using the estimate

$$\left(W_A(t_i), \int_{t_{i-1}}^{t_i} AY_\epsilon(s)ds\right) \le C \int_{t_{i-1}}^{t_i} \|Y_\epsilon(s)\|^2 ds$$

which follows from (1.3), we get after some computations the estimate (12).

Step 2. We prove existence of the limits of $Y_{\epsilon}(t)$ and $\eta_{\epsilon}(t)$ as $\epsilon \to 0$.

We first prove that the sequence $\{Y_\epsilon\}$ is equi-continuous in C([0,T];H). Let h>0, then

$$\frac{d}{dt} (Y_{\epsilon}(t+h) - Y_{\epsilon}(t)) + A(Y_{\epsilon}(t+h) - Y_{\epsilon}(t)) + F(X_{\epsilon}(t+h)) - F(X_{\epsilon}(t)) + \beta_{\epsilon}(X_{\epsilon}(t+h)) - \beta_{\epsilon}(X_{\epsilon}(t)) = 0.$$

Taking into account that W_A is \mathbb{P} -a.s. continuous in H (by (3)), we may assume that

$$\sup_{t \in [0,T]} |W_A(t+h) - W_A(t)| \le \delta(h) \to 0 \quad \text{as } h \to 0.$$

We deduce by the monotonicity of β_{ϵ} and because F is Lipschitz that

$$|Y_{\epsilon}(t+h) - Y_{\epsilon}(t)| \le C\delta(h), \quad \forall t \in [0,T], h > 0, \epsilon > 0.$$
(14)

So $\{Y_{\epsilon}\}$ is equi-continuous. To apply the Ascoli–Arzelà Theorem we have to prove that for each $t \in [0, T]$ the set $\{Y_{\epsilon}(t)\}_{\epsilon>0}$ is pre-compact in H. To prove this, choose for any $\epsilon > 0$ a sequence $\{f_n^{\epsilon}\} \subset L^2(0, T; V)$ such that

$$|f_n^{\epsilon} - \beta_{\epsilon}(Y_{\epsilon} + W_A)|_{L^1(0,T;H)} \le \frac{1}{n}, \quad n \in \mathbb{N}.$$

On the other hand, for each $n \in \mathbb{N}$ the set

$$M_n := \left\{ \int_0^t e^{-A(t-s)} f_n^{\epsilon} ds + e^{-At} x : \epsilon > 0 \right\}$$

is compact in H because $\{f_n^{\epsilon}\}$ is bounded in $L^2(0,T;H)$ for each $n \in \mathbb{N}$. This implies that for any $\delta > 0$ there are $N(n) \in \mathbb{N}$ and $\{u_i^n\}_{i=1,\ldots,N(n)} \subset H$ such that

$$\bigcup_{i=1}^{N(n)} B(u_i^n, \delta) \supset M_n.$$

 $(B(u_i^n, \delta))$ is the ball with center u_i^n and radius δ .) Therefore

$$\left\{Y_{\epsilon}(t) := \int_0^t e^{-A(t-s)} f_n^{\epsilon} ds + e^{-At} x: \ \epsilon > 0\right\} \subset \bigcup_{i=1}^{N(n)} B(u_i^n, \delta + n^{-1}).$$

Since n is arbitrary we infer that for each $\delta > 0$, the set $\{Y_{\epsilon}(t)\}_{\epsilon>0}$ can be covered by a finite number of balls of radius δ and therefore it is precompact in H as claimed. Then by (14) and the Ascoli–Arzelà Theorem we infer that on a subsequence, $Y_{\epsilon} \to Y$ strongly in C([0,T];H) and weakly in $L^2(0,T;V)$. Moreover, thanks to Helly's Theorem we have that there is $\eta \in BV([0,T];H)$ such that for $\epsilon \to 0$

$$\int_0^t \beta_{\epsilon}(X_{\epsilon}(s))ds \to \eta(t) \text{ weakly in } H, \ \forall t \in [0,T],$$
(15)

which implies that

$$\int_0^t (\beta_\epsilon(X_\epsilon(s)), Z(s)) ds \to \int_0^t (d\eta(s), Z(s)), \quad \forall \ Z \in C([0, T]; K).$$
(16)

Letting $\epsilon \to 0$ into the identity

$$Y_{\epsilon}(t) + \int_0^t (AY_{\epsilon}(s + F(Y_{\epsilon}(s)))ds + \int_0^t \beta_{\epsilon}(Y_{\epsilon}(s) + W_A(s)))ds = x,$$

we see that (Y, η) satisfy (7). Finally, by (16) and the monotonicity of β_{ϵ} we have (recall that $\beta_{\epsilon}(Z(s)) = 0$),

$$(\beta_{\epsilon}(Y_{\epsilon}(s) + W_A(s)), Y_{\epsilon}(s) + W_A(s) - Z(s)) \ge 0, \quad \forall Z \in C([0, T; K)]$$

we see that (8) holds for $X = Y + W_A$, i.e.,

$$\int_{0}^{t} (d\eta(s), Y(s) + W_{A}(s) - Z(s)) \ge 0, \quad \forall \ Z \in C([0, T]; K).$$
(17)

On the other hand, by Itô's formula in (9) we get

$$\mathbb{E}|X_{\epsilon}(t)|^{2} + \int_{0}^{t} \mathbb{E}||X_{\epsilon}(s)||^{2} ds \leq C, \forall \epsilon > 0,$$

which clearly implies that $X \in C_W([0,T];H) \cap L^2_W(0,T,V)$. This completes the proof of existence.

Uniqueness. Assume that (Y_1, η_1) , (Y_2, η_2) are two strong solutions of (1). Then by condition (iv) in Definition 1 we have

$$\int_{0}^{t} (d(\eta_{1}(s) - \eta_{2}(s)), Y_{1}(s) - Y_{2}(s)) ds \ge 0 \quad \forall t \in [0, T].$$

This yields

$$\int_0^t d(Y_1(s) - Y_2(s), \\ \int_0^s (A(Y_1(\tau) - Y_2(\tau)) + F(X_1(\tau) - F(X_2(\tau))d\tau, Y_1(s) - Y_2(s)) \le 0$$

and by integration we obtain that (see Lemma 1 below)

$$\frac{1}{2}|Y_1(t) - Y_2(t)|^2 + \int_0^t (A(Y_1 - Y_2) + F(X_1) - F(X_2), Y_1 - Y_2)ds \le 0,$$

 $\forall t \in [0, T]$, which implies via Gronwall's lemma that $Y_1 = Y_2$.

In particular, the latter implies that the sequence $\{\epsilon\}$ founded before is independent of ω and so there is indeed a unique pair satisfying Definition 1.

LEMMA 1 Let $y \in C([0,T];H) \cap L^2(0,T;V)$ be such that

$$y(t) + \int_0^t Ay(s)ds \in BV([0,T];H).$$

Then

$$\int_{0}^{t} (d(y(s) + \int_{0}^{s} A(y(\tau)d\tau), y(s)))$$

= $\frac{1}{2} |y(t)|^{2} - \frac{1}{2} |x|^{2} + \int_{0}^{t} (Ay(s), y(s))ds, \quad \forall t \in [0, T].$ (18)

Proof. Of course (18) is true if $y \in C([0,T]; V)$ which is not, however, the case here. Approximating y by a sequence $\{y_n\} \in C([0,T]; V)$ which is strongly convergent in C([0,T]; H) and such that the functions

$$t \to y_n(t) + \int_0^t A y_n(s) ds,$$

have uniform bounded variation from [0, T] to H, we may get (18) by passing to limit in the corresponding equality for y_n .

REMARK 1 It is not clear whether Theorem 1 remains valid in absence of Hypothesis 1(iii) or for if Q = I. (This happens, however, for the obstacle problem, see Nualart and Pardoux, 1992; Zambotti, 2001).

3. Invariant measures

Let X = X(t, x) be the solution of (1) obtained above. We denote by P_t : $C_b(H) \rightarrow C_b(H)$ the corresponding transition semigroup,

$$P_t\varphi(x) = \mathbb{E}[\varphi(X(t,x))], \quad x \in K.$$
(19)

PROPOSITION 1 Assume that Hypothesis 1 holds. Then there is at least one invariant measure ν for P_t with support included in $K \cap V$. If in addition there exists $\gamma_1 > 0$ such that

$$(A(u-v) + F(u) - F(v), u-v) \ge \gamma_1 |u-v|^2, \quad \forall \ u, v \in D(A),$$
(20)

the invariant measure ν is unique.

Proof. We come back to the approximating equation (9) and denote by P_t^{ϵ} the corresponding transition semigroup, i.e.,

$$P_t^{\epsilon}\varphi(x) = \mathbb{E}[\varphi(X_{\epsilon}(t,x))], \quad x \in H,$$
(21)

and by N_{ϵ} the corresponding Kolmogorov operator,

$$(N_{\epsilon}\varphi)(x) = \frac{1}{2} \operatorname{Tr} \left[QD^{2}\varphi\right] - (Ax + F(x) + \beta_{\epsilon}(x), D\varphi(x)).$$

It is known that under our conditions there is at least one invariant measure ν_{ϵ} for P_t^{ϵ} . We claim that $\{\nu_{\epsilon}\}_{\epsilon>0}$ is tight. Indeed, by the invariance of ν_{ϵ} it follows that $\int_H (N_{\epsilon}\varphi)(x)\nu_{\epsilon}(dx) = 0$, so that

$$\int_{H} (\|x\|^2 + (F_{\epsilon}(x) + \beta_{\epsilon}(x), x) \nu_{\epsilon}(dx) \le \operatorname{Tr} Q.$$
(22)

Since V is compactly embedded in H, we infer that $\{\nu_{\epsilon}\}_{\epsilon>0}$ is tight. Let ν be a weak limit point of $\{\nu_{\epsilon}\}_{\epsilon>0}$; then one can easily check that ν is an invariant measure for P_t and

$$\int_{H} (\|x\|^2 + (F(x), x)) \nu(dx) \le \text{Tr } Q,$$
(23)

which implies supp $\nu \subset V$.

On the other hand, we have

$$(\beta_{\epsilon}(x), x) = (\beta_{\epsilon}(x), x - \Pi_{K}(x)) + (\beta_{\epsilon}(x), \Pi_{K}(x))$$
$$\geq (\beta_{\epsilon}(x), x - \Pi_{K}(x)) = \frac{1}{\epsilon} |x - \Pi_{K}(x)|^{2}$$

and, taking into account (22), this implies

$$\int_{K^c} |x - \Pi_K(x)|^2 \nu(dx) = 0$$

and therefore supp $\nu \subset K$ as claimed. Finally, if (20) holds the invariant measure is unique by a standard argument (see Da Prato and Zabczyk, 1996).

4. The infinitesimal generator

This section is devoted to study the relationship between the infinitesimal generator N of P_t and the differential operator N_0 defined by (5).

To this end we shall also assume that K has a special form precised in Hypothesis 2 below

HYPOTHESIS 2 There exists $T \in L(H)$ self-adjoint, positive and r > 0 such that

$$K = \{ x \in H : (Tx, x) \le r^2, \quad \forall x \in H \}.$$

Then the boundary of K is given by

$$\partial K = \{ x \in H : (Tx, x) = r^2, \quad \forall x \in H \},\$$

while $N_K(x) = \{\lambda T x\}_{\lambda>0}$ is the normal cone to K.

THEOREM 2 Assume that Hypotheses 1 and 2 are fulfilled. Let $\varphi \in C_b^2(H) \cap D(N)$ be such that $A\varphi \in C_b^1(H)$ and

 $(D\varphi(x), Tx) = 0, \text{ on } \partial K.$

Then $\varphi \in D(N)$ and

$$N\varphi = \frac{1}{2} \operatorname{Tr} \left[QD^2 \varphi \right] - (x, AD\varphi) - (F(x), D\varphi).$$
(24)

Proof. Let $\varphi \in C_b^2(H) \cap D(N)$. By (9), applying Itô's formula, we have

$$\varphi(X_{\epsilon}(t)) - \varphi(x) + \int_{0}^{t} (AX_{\epsilon}(s) + F(X_{\epsilon}(s)), D\varphi(X_{\epsilon}(s))) ds + \int_{0}^{t} (\beta_{\epsilon}(X_{\epsilon}(s)), D\varphi(X_{\epsilon}(s))) ds = \frac{1}{2} \int_{0}^{t} \operatorname{Tr} \left[QD^{2}\varphi(X_{\epsilon}(s))\right] ds$$
(25)
+
$$\int_{0}^{t} (D\varphi(X_{\epsilon}(s)), \sqrt{Q} \ dW(s)) ds.$$

Invoking (15) and (16) we have for $\epsilon \to 0$

$$\varphi(X_{\epsilon}(t)) \to \varphi(X(t)), \quad \text{uniformly in } t, \mathbb{P}\text{-a.s.},$$
(26)

$$(AX_{\epsilon}(t) + F(X_{\epsilon}(t)), D\varphi(X_{\epsilon}(t))) \rightarrow (X(t), AD\varphi(X(t))) + (F(X(t)), D\varphi(X(t))), \quad \mathbb{P}\text{-a.s.}$$
(27)

$$\operatorname{Tr}\left[QD^{2}\varphi(X_{\epsilon}(t))\right] \to \operatorname{Tr}\left[QD^{2}\varphi(X(t))\right], \quad \mathbb{P}\text{-a.s.}.$$
(28)

$$\int_0^t (\beta_\epsilon(s), D\varphi(X_\epsilon(s)) \to \int_0^t (d\eta(s), D\varphi(X(s))), \quad \mathbb{P}\text{-a.s.}.$$
(29)

Then, letting $\epsilon \rightarrow 0$ in (25) we obtain by (27)–(29),

$$\varphi(X(t)) - \varphi(x) + \int_0^t (AX(s) + F(X(s)), D\varphi(X(s))) ds$$

+
$$\int_0^t (d\eta(s), D\varphi(X(s))) ds = \frac{1}{2} \int_0^t \text{Tr} \left[QD^2\varphi(X(s))\right] ds$$

+
$$\int_0^t (D\varphi(X(s)), \sqrt{Q} \, dW(s)) ds, \quad \mathbb{P}\text{-a.s.}.$$
 (30)

We claim that

$$\int_0^t (d\eta(s), D\varphi(X(s)))ds = 0, \quad \forall \ t \in [0, T], \ \mathbb{P}\text{-a.s.}.$$
(31)

Let $I = \{s \in (0,t) : X(s) \in \mathring{K}\}$ and $I^c = (0,t) \setminus I = \{s \in (0,t) : X(s) \in \partial K\}$. Then by (8) we see that

$$\int_0^t (d\eta(s), X(s) - \Pi_K(X(s) \pm \lambda D\varphi(X(s))) ds \ge 0, \quad \forall \ \lambda > 0,$$
(32)

which implies, for λ sufficiently small,

$$\mp \int_{I} (d\eta(s), D\varphi(X(s))) + \frac{1}{\lambda} \int_{I^c} (d\eta(s), X(s) - \Pi_K(X(s) \pm \lambda D\varphi(X(s))) \ge 0.$$
(33)

Now we want let $\lambda \to 0$ in the second term. For this we note that

$$\Pi_K(x) = \frac{rx}{|T^{1/2}x|}, \quad \forall \ x \in H \setminus K$$

and

$$D\Pi_K(x) = \frac{r}{|T^{1/2}x|} - r\frac{x \otimes Tx}{|T^{1/2}x|^3}, \quad \forall x \in H \setminus K.$$

So, if $s \in I^c$ we have

$$\lim_{\lambda \to 0} \frac{1}{\lambda} \left(X(s) - \Pi_K(X(s) \pm \lambda D\varphi(X(s))) = \mp D\Pi_K(x) \cdot D\varphi(X(s)) \right) \\ = \mp D\varphi(X(s)) \pm r^{-2} (TX(s), D\varphi(X(s))) T^{1/2} X(s) = \mp D\varphi(X(s)),$$

because $X(s) \in \partial K$ and $(D\varphi(X(s)), Tx) = 0$ on ∂K . Now, letting $\lambda \to 0$ in (33) yields

$$\int_0^t (d\eta(s), D\varphi(X(s)))ds = 0,$$

and (25) follows.

Finally, (30) becomes

$$\begin{aligned} \varphi(X(t)) &- \varphi(x) + \int_0^t (AX(s) + F(X(s)), D\varphi(X(s))) ds \\ &= \frac{1}{2} \int_0^t \text{Tr} \left[QD^2 \varphi(X(s)) \right] ds + \int_0^t (D\varphi(X(s)), \sqrt{Q} \ dW(s)) ds, \quad \mathbb{P}\text{-a.s.} \end{aligned}$$

and since $AD\varphi(X(s)) \in C([0,T] H)$ the latter yields

$$\lim_{t \to 0} \frac{1}{t} \left(\mathbb{E}[\varphi(X(t,x))] - \varphi(x) \right)$$
$$= -(x, AD\varphi(x)) - (F(x), D\varphi(x)) + \frac{1}{2} \operatorname{Tr} \left[QD^2 \varphi(x) = N_0 \varphi(x) \right],$$

as claimed.

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5. An example

-1

Consider equation (1) in $H = L^2(\mathcal{O})$

$$\begin{cases} dX - \Delta X dt + f(X) dt + \partial I_K(X) dt \ni \sqrt{Q} \, dW(t), \\ X(0) = x \quad \text{in } \mathcal{O}, \quad X = 0 \quad \text{on } \partial \mathcal{O}, \end{cases}$$
(34)

where \mathcal{O} is an open bounded domain of \mathbb{R}^d ,

$$K = \{ x \in L^2(\mathcal{O}) : |x|_{L^2(\mathcal{O})} \le 1 \},\$$

 $f: \mathbb{R} \to \mathbb{R}$ is a Lipschitz continuous function such that $f(r)r \geq -\gamma, \ \gamma > 0$, for all $r \in \mathbb{R}$ and $Q = -A^{-l}, \ l > 0, \ A = -\Delta, \ D(A) = H^2(\mathcal{O}) \cap H^1_0(\mathcal{O}).$

Here W is a Wiener process in $L^2(\mathcal{O})$,

$$W(t) = \sum_{j=1}^{\infty} \beta_j(t) e_j,$$

where (e_j) is an orthonormal basis of eigenfunctions for A, $Ae_j = \lambda_j e_j$ and (β_j) is a system of independent Brownian motions in a filtered probability space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P}).$

In order to satisfy Hypothesis 1(iii) we shall assume also that

$$\sum_{j=1}^{\infty} \lambda_j^{1-l} < \infty.$$

For d = 1 the latter holds if l > 1/2.

Then Theorem 1 applies and (34) has a unique solution X(t, x) in the sense of Definition 1. So, we can consider the transition semigroup $P_t\varphi(x) =$

 $\mathbb{E}[\varphi(X(t,x))]$. By Theorem 2 if $\varphi \in D(N_0)$, that is if it is sufficiently regular and satisfy a Neumann condition on the boundary of K, then the infinitesimal generator N associated with semigroup P_t has the explicit form

$$(N\varphi)(x) = \frac{1}{2} \sum_{j=1}^{\infty} \lambda_j^{-l} (D^2 \varphi(x) e_j, e_j) - \sum_{j=1}^{\infty} \lambda_j (D\varphi(x), e_j) - (f(x), D\varphi(x)), \quad (35)$$

(Here (\cdot, \cdot) is the scalar product in $H = L^2(\mathcal{O})$.)

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